



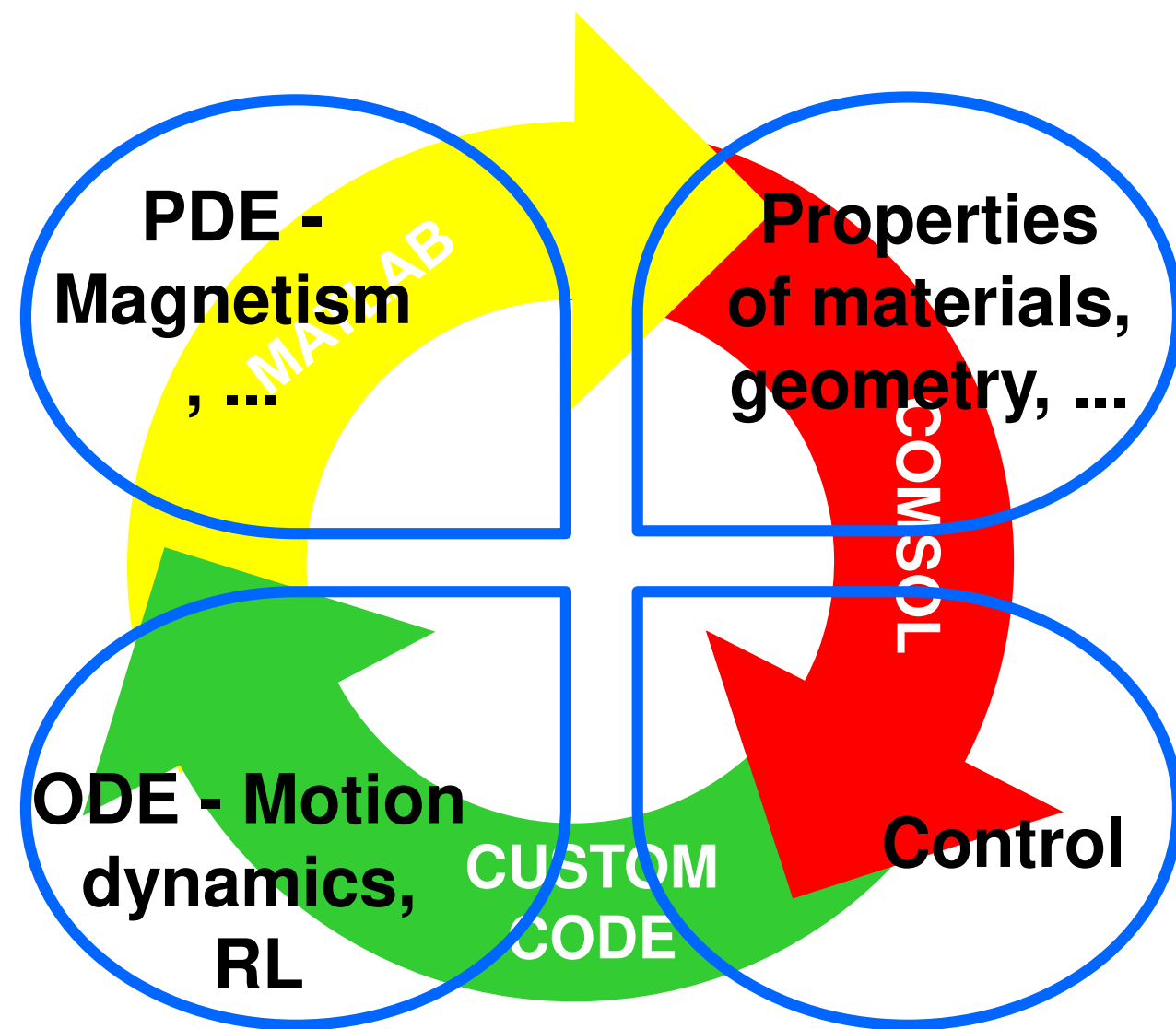
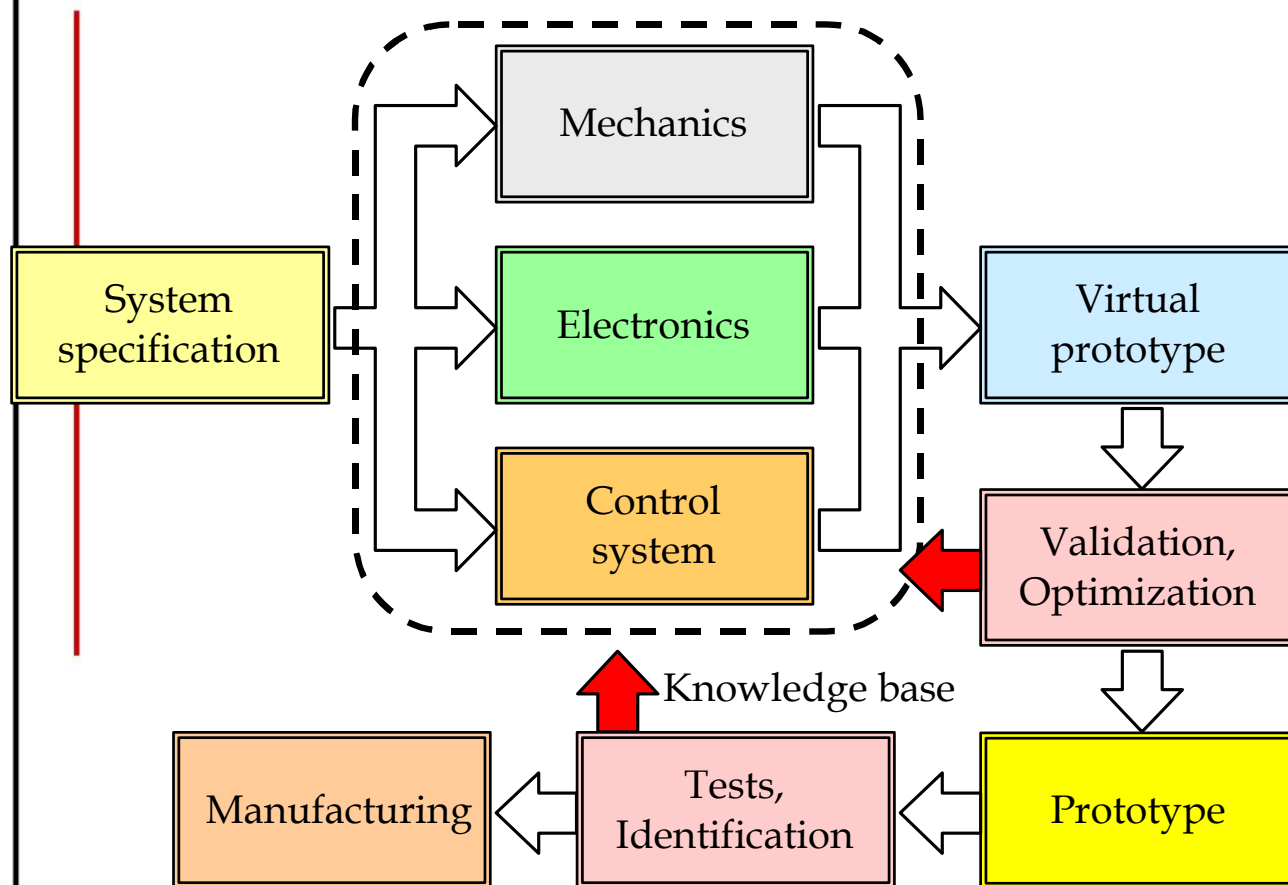
AKADEMIA GÓRNICZO-HUTNICZA
IM. STANISŁAWA STASZICA W KRAKOWIE
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Department of Automatic Control and Robotics

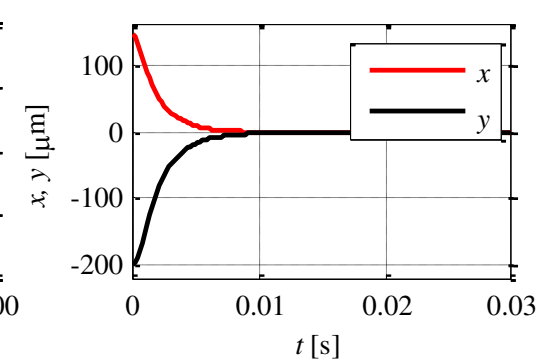
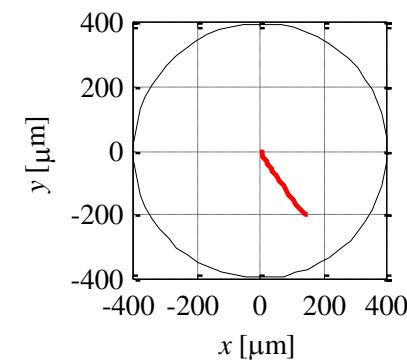
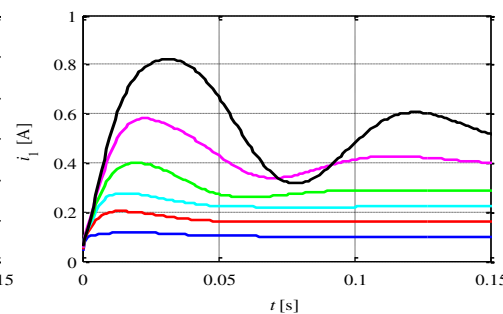
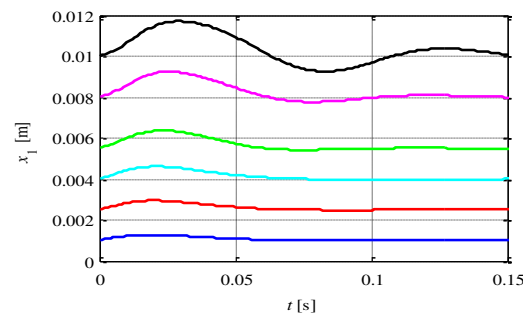
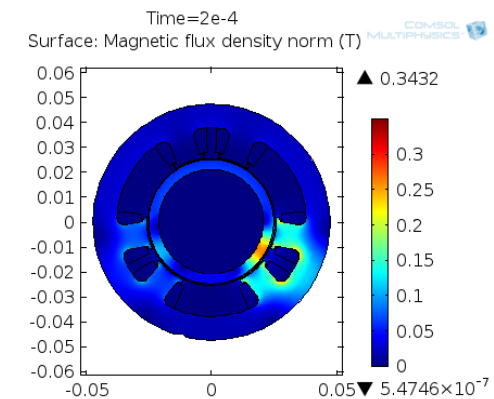
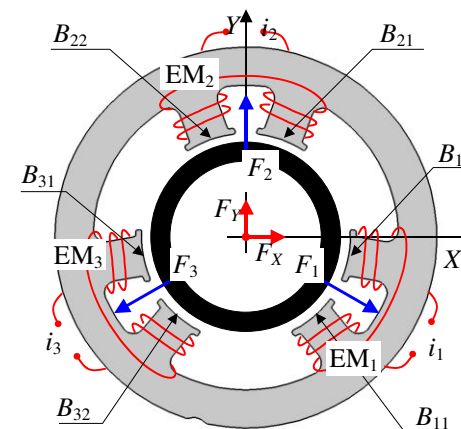
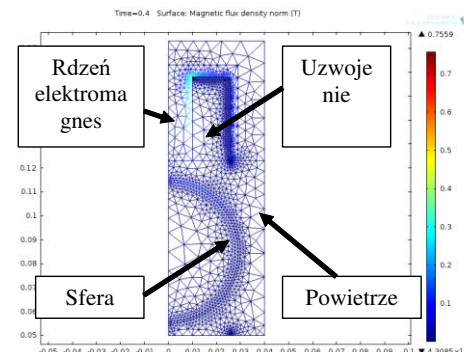
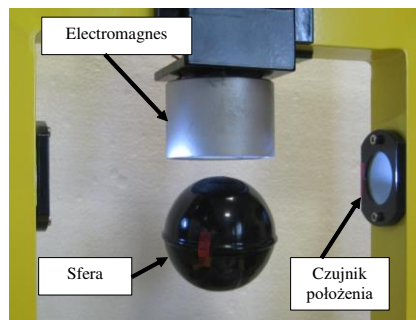
Active Magnetic Levitation Active Magnetic Bearing



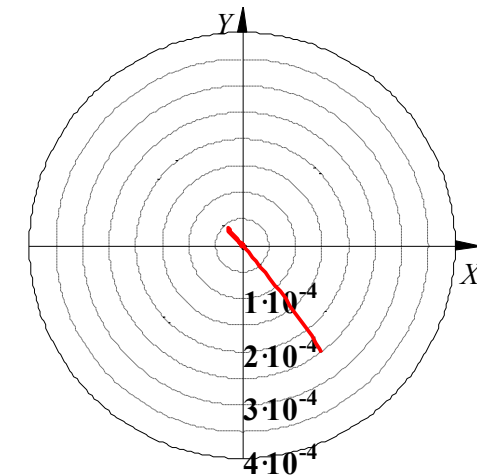
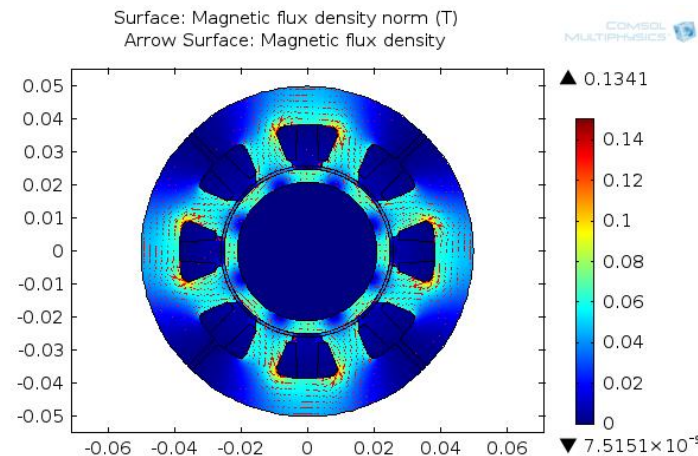
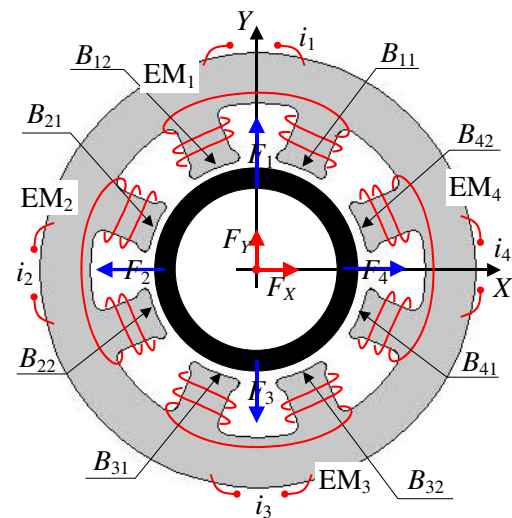
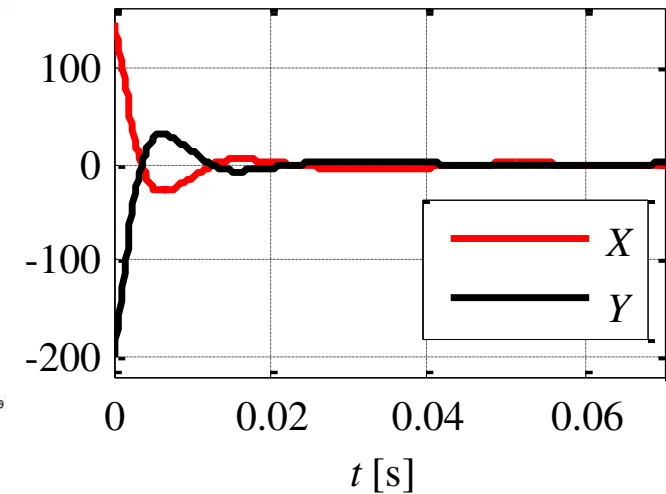
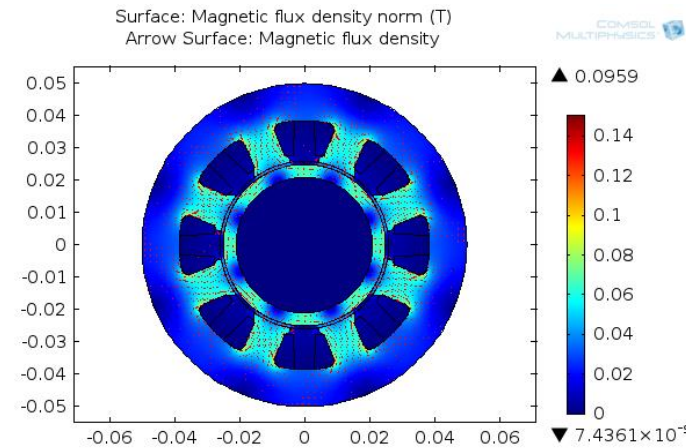
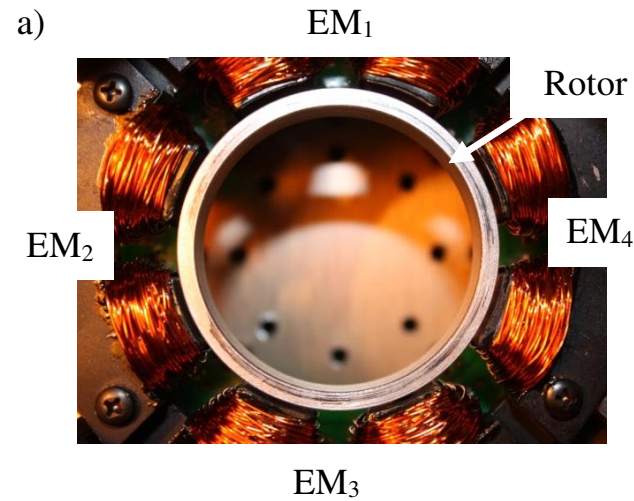
From concept to prototype



Virtual prototypes – suspension and bearing



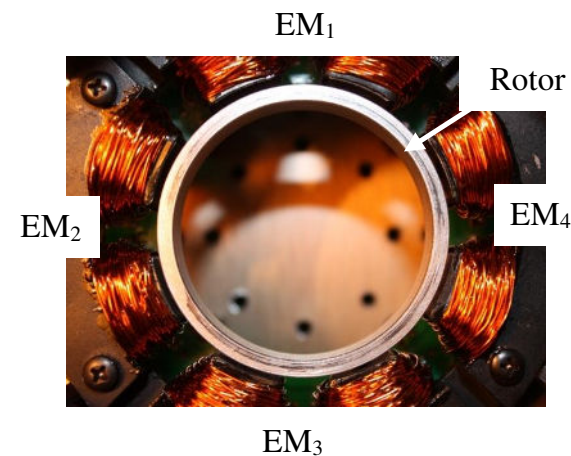
Virtual prototypes – suspension and bearing



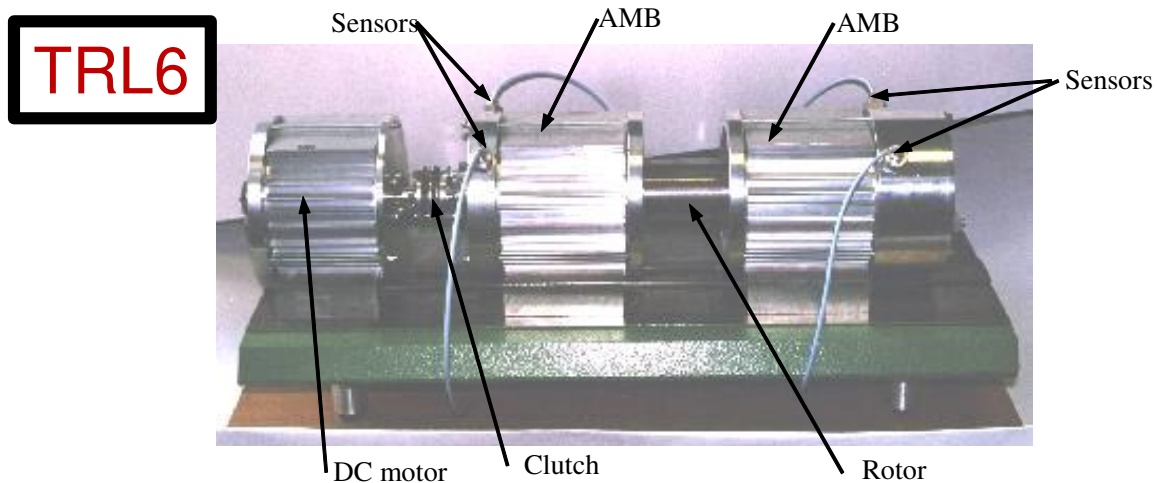
Laboratory test-rigs



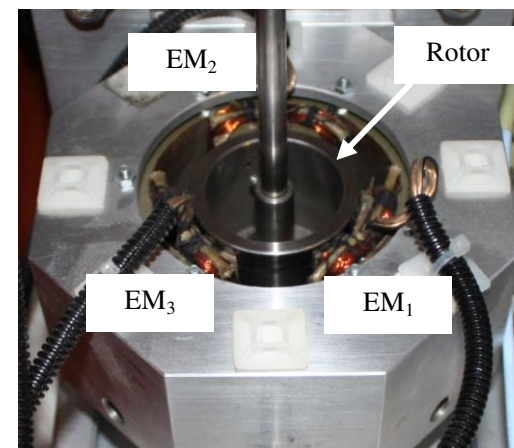
TRL9



TRL6

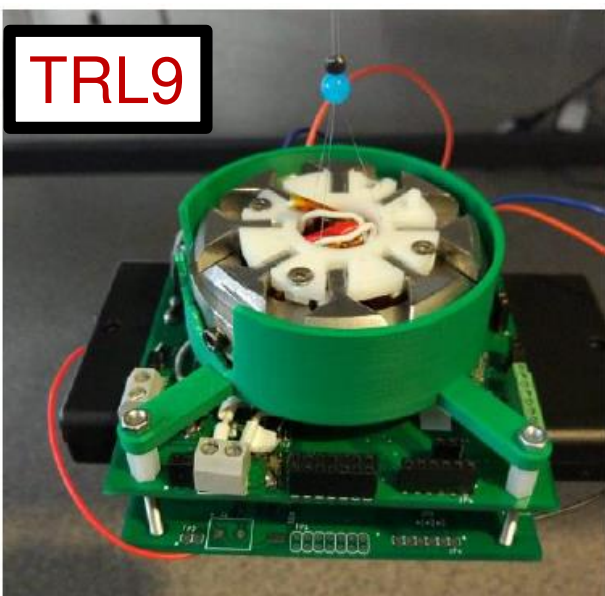
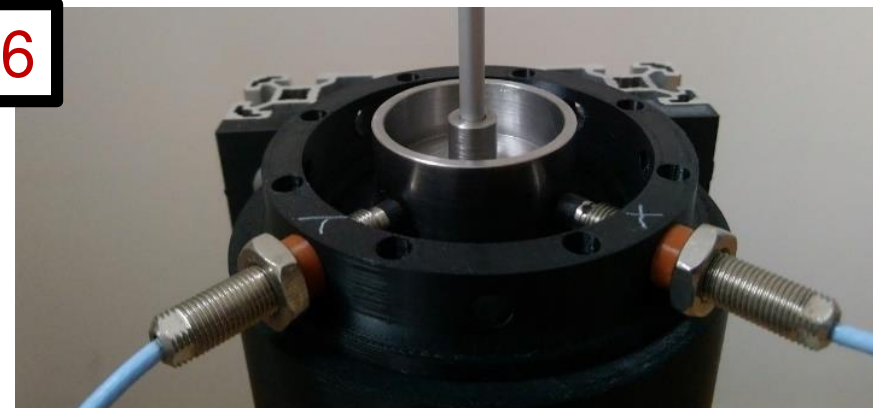
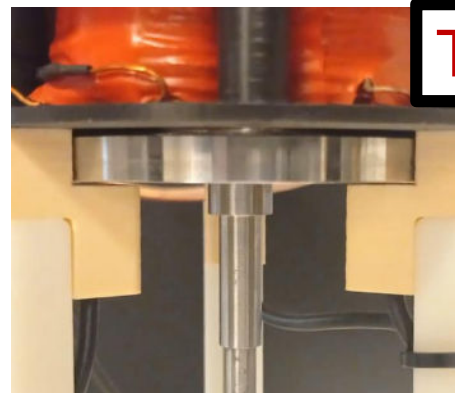
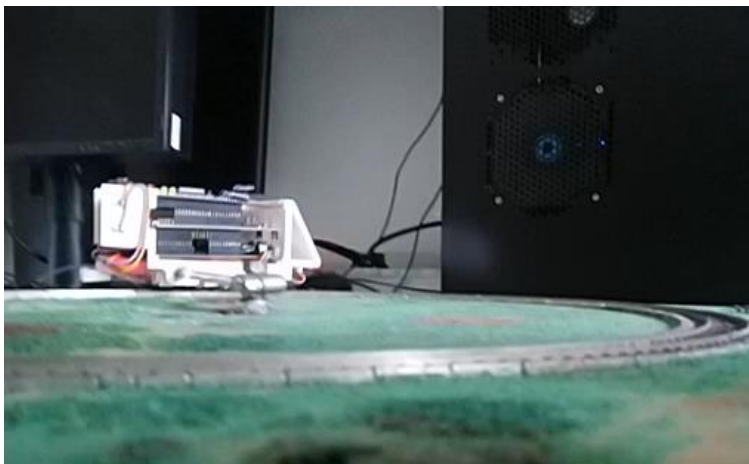


TRL6

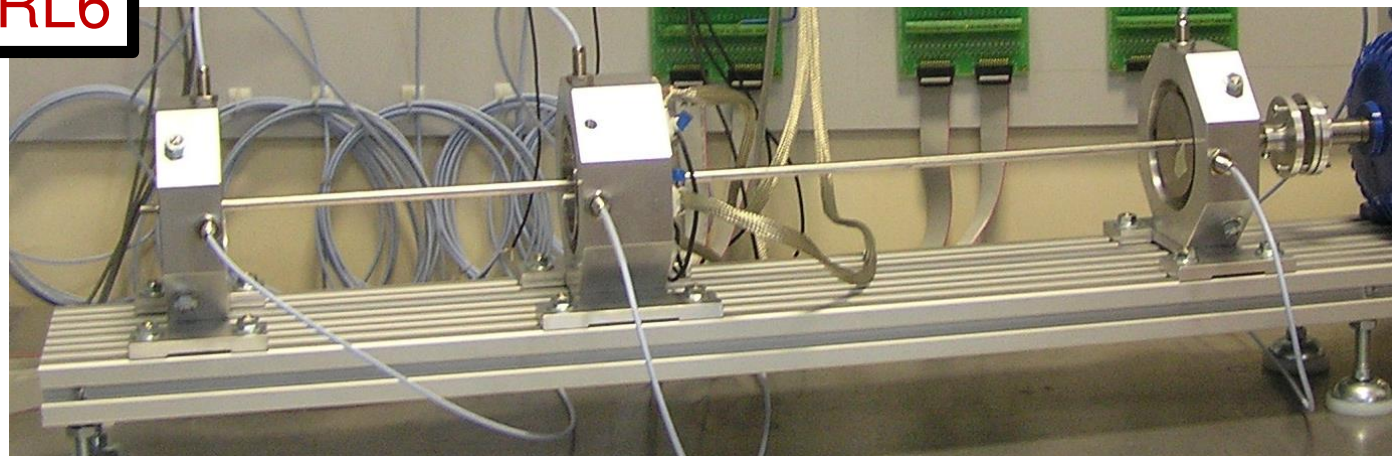


TRL6

Laboratory test-rigs

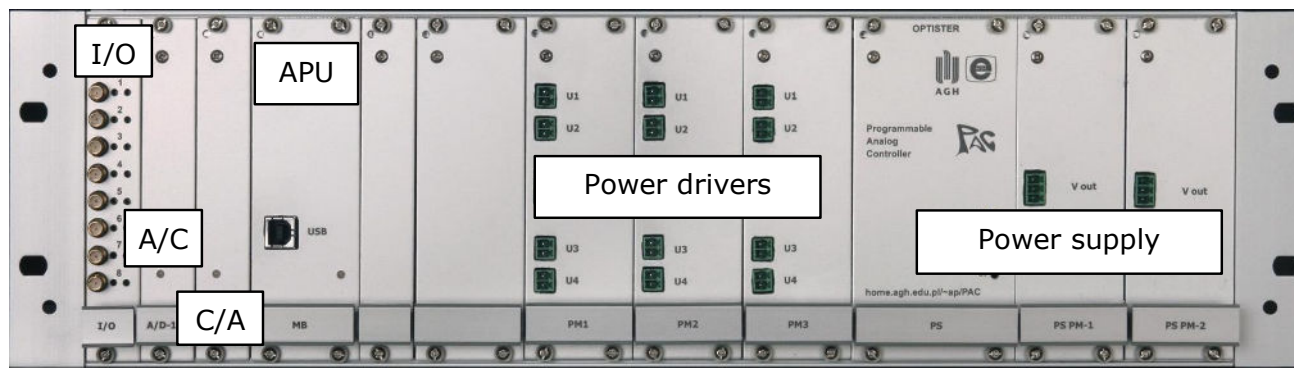


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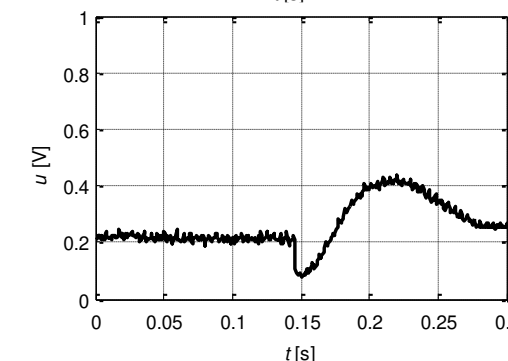
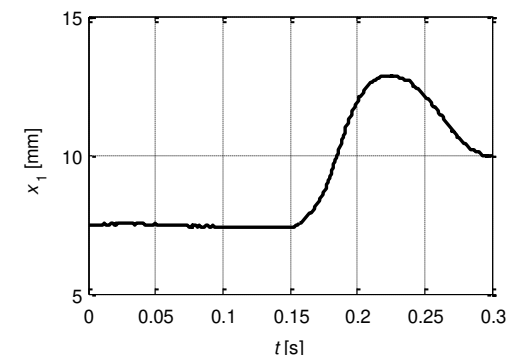


Programmable Automation Controller (PAC)

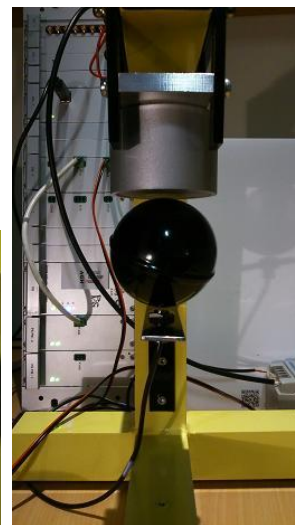
TRL9



Modular architecture (I/O, A/C, D/A, computing module, power amplifiers, logic module, stepper motor module, power modules)
Configurable by hardware and software
Hard real-time regime
Parallel signal processing
Analog and digital signal processing
USB, Ethernet communication
Industry standard



Reconfiguration of controller parameters in w 1.34 microseconds



Offer for cooperation

- Design of electromagnetic actuators, electromagnetic grippers
- Design of active and hybrid magnetic bearings for various applications
- Industrial controllers with data acquisition, diagnostics and controller adaptation
- Reconfigurable instrumentation for measurement and control tasks
- Conventional and Intelligent nonlinear control methods
- Algorithms for control and diagnostics of equipment, evaluation of control quality
- Interdisciplinary analysis of existing and newly designed equipment
- Fabrication of laboratory models and pre-production prototypes

Contact



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